# The View Matrix <br> Lecture 24 

Robb T. Koether<br>Hampden-Sydney College

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## Outline

(9) The View Matrix
(2) The Eye Coordinate System
(3) Calculating the View Matrix
4. An Example
(5) Assignment

## Outline

(1) The View Matrix
(2) The Eye Coordinate System
(3) Calculating the View Matrix

4 An Example
(5) Assignment

## The View Matrix

## Definition (The View Matrix)

The view matrix is the matrix that transforms the world coordinates into the eye coordinates.

- The function lookAt () creates the view matrix.
- The parameters to lookAt () are
- The eye point eye,
- The look point look,
- The up vector up.


## The View Matrix

- In earlier versions of OpenGL, the libraries maintained the modelview matrix on the modelview stack.
- The top matrix was the product of the model matrix and the view matrix.
- It was critically important to push the view matrix first, followed by the various model matrices.
- The function gluLookAt (), in the glu library, created the view matrix and pushed it onto the modelview stack.
- Now all of that is handled by the programmer.


## The lookAt () Function

## The setView() Function

```
void setView()
    GLfloat yaw_r = yaw * DEG_TO_RAD;
    GLfloat pitch_r = pitch * DEG_TO_RAD;
    eye[0] = look[0] + eye_dist * sinf(yaw_r) * cosf(pitch_r);
    eye[1] = look[1] + eye_dist * sinf(pitch_r);
    eye[2] = look[2] + eye_dist * cosf(yaw_r) * cosf(pitch_r);
    view = lookAt(eye, look, up);
    glUniformMatrix4fv(view_loc, 1, GL_FALSE, view);
    glUniform3fv(eye_loc, 1, eye);
}
```


## The lookAt () Function

## The setView() Function

```
void setView()
    GLfloat yaw_r = yaw * DEG_TO_RAD;
    GLfloat pitch_r = pitch * DEG_TO_RAD;
    eye = look + vec3(eye_dist * sinf(yaw_r) * cosf(pitch_r),
        eye_dist * sinf(pitch_r),
        eye_dist * cosf(yaw_r) * cosf(pitch_r));
        view = lookAt(eye, look, up);
        glUniformMatrix4fv(view_loc, 1, GL_FALSE, view);
        glUniform3fv(eye_loc, 1, eye);
    }
```


## Outline

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## The uvw Eye Coordinate System

- In the eye coordinate system, the "eye" is
- Located at the origin
- Looking in the negative $z$-direction.


## The uvw Eye Coordinate System

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- The view matrix actually moves the entire scene in front of the eye, which is always at the origin, always looking down the negative $z$-axis.


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- Located at the origin
- Looking in the negative z-direction.
- The view matrix actually moves the entire scene in front of the eye, which is always at the origin, always looking down the negative $z$-axis.
- But it is more intuitive to think of the view matrix as moving the eye from the origin to the eye position.
- The two transformations are inverses of each other.


## The uvw Eye Coordinate System

- Let the vectors $\mathbf{u}, \mathbf{v}$, and $\mathbf{w}$ be unit vectors in a RHS, expressed in world coordinates, located at the eye position, and oriented so that the eye is looking along -w towards the look point.


## The uvw Eye Coordinate System

- Let the vectors $\mathbf{u}, \mathbf{v}$, and $\mathbf{w}$ be unit vectors in a RHS, expressed in world coordinates, located at the eye position, and oriented so that the eye is looking along $-\mathbf{w}$ towards the look point.
- We will calculate $\mathbf{u}, \mathbf{v}$, and $\mathbf{w}$ from eye $(E)$, look ( $L$ ), and up (up).


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- We will calculate $\mathbf{u}, \mathbf{v}$, and $\mathbf{w}$ from eye ( $E$ ), look ( $L$ ), and up (up).
- These vectors are key to defining the view matrix.


## The uvn Eye Coordinate System



- Given the eye point $E$, the look point $L$, and the up vector up.


## The uvn Eye Coordinate System



- We need to determine the basic unit vectors $\mathbf{u}, \mathbf{v}$, and $\mathbf{w}$ of the eye coordinate system.


## The uvn Eye Coordinate System



- They correspond to the $x-, y$-, and $z$-axes of that system.


## The uvn Eye Coordinate System



- Let $E$ be the eye position, $L$ the look point, and up the up vector.


## The uvn Eye Coordinate System



- Define $\mathbf{w}^{\prime}=E-L$ and $\mathbf{w}=\frac{\mathbf{w}^{\prime}}{\left|\mathbf{w}^{\prime}\right|}$.


## The uvn Eye Coordinate System



- The vector $\mathbf{u}$ must be perpendicular to $\mathbf{w}$ and up.
- Define $\mathbf{u}^{\prime}=\mathbf{u p} \times \mathbf{w}$ and $\mathbf{u}=\frac{\mathbf{u}^{\prime}}{\left|\mathbf{u}^{\prime}\right|}$.


## The uvn Eye Coordinate System



- We cannot assume that up is perpendicular to w.
- Therefore, let $\mathbf{v}$ be the unit vector $\mathbf{v}=\mathbf{w} \times \mathbf{u}$.


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## The View Matrix

- Let the vectors $\mathbf{i}, \mathbf{j}$, and $\mathbf{k}$ be the basic unit vectors in the eye coordinate system.
- The transformation to the eye coordinate system is determined by the world vectors $\mathbf{u}, \mathbf{v}$, and $\mathbf{w}$.
- The view matrix view must transform $\mathbf{u}, \mathbf{v}, \mathbf{w}$ into $\mathbf{i}, \mathbf{j}, \mathbf{k}$ :

$$
\begin{aligned}
\text { view } \cdot \mathbf{u} & =\mathbf{i} \\
\text { view } \cdot \mathbf{v} & =\mathbf{j} \\
\text { view } \cdot \mathbf{w} & =\mathbf{k}
\end{aligned}
$$

## The View Matrix

- That is,

$$
\text { view } \cdot \mathbf{u}=\left(\begin{array}{cccc}
v_{11} & v_{12} & v_{13} & a \\
v_{21} & v_{22} & v_{23} & b \\
v_{31} & v_{32} & v_{33} & c \\
0 & 0 & 0 & 1
\end{array}\right)\left(\begin{array}{c}
u_{x} \\
u_{y} \\
u_{z} \\
0
\end{array}\right)=\left(\begin{array}{l}
1 \\
0 \\
0 \\
0
\end{array}\right)=\mathbf{i}
$$

- That is,

$$
\begin{aligned}
& \left(v_{11}, v_{12}, v_{13}\right) \cdot \mathbf{u}=1, \\
& \left(v_{21}, v_{22}, v_{23}\right) \cdot \mathbf{u}=0, \\
& \left(v_{31}, v_{32}, v_{33}\right) \cdot \mathbf{u}=0 .
\end{aligned}
$$

- That is,

$$
\begin{aligned}
& \left(v_{11}, v_{12}, v_{13}\right) \cdot \mathbf{u}=1, \\
& \left(v_{21}, v_{22}, v_{23}\right) \cdot \mathbf{u}=0, \\
& \left(v_{31}, v_{32}, v_{33}\right) \cdot \mathbf{u}=0
\end{aligned}
$$

- Recall that

$$
\begin{aligned}
\mathbf{u} \cdot \mathbf{u} & =1 \\
\mathbf{v} \cdot \mathbf{u} & =0 \\
\mathbf{w} \cdot \mathbf{u} & =0
\end{aligned}
$$

## The View Matrix

- And,

$$
\text { view } \cdot \mathbf{v}=\left(\begin{array}{cccc}
v_{11} & v_{12} & v_{13} & a \\
v_{21} & v_{22} & v_{23} & b \\
v_{31} & v_{32} & v_{33} & c \\
0 & 0 & 0 & 1
\end{array}\right)\left(\begin{array}{c}
v_{x} \\
v_{y} \\
v_{z} \\
0
\end{array}\right)=\left(\begin{array}{l}
0 \\
1 \\
0 \\
0
\end{array}\right)=\mathbf{j}
$$

- That is,

$$
\begin{aligned}
& \left(v_{11}, v_{12}, v_{13}\right) \cdot \mathbf{v}=0, \\
& \left(v_{21}, v_{22}, v_{23}\right) \cdot \mathbf{v}=1, \\
& \left(v_{31}, v_{32}, v_{33}\right) \cdot \mathbf{v}=0 .
\end{aligned}
$$

- That is,

$$
\begin{aligned}
& \left(v_{11}, v_{12}, v_{13}\right) \cdot \mathbf{v}=0, \\
& \left(v_{21}, v_{22}, v_{23}\right) \cdot \mathbf{v}=1, \\
& \left(v_{31}, v_{32}, v_{33}\right) \cdot \mathbf{v}=0 .
\end{aligned}
$$

- Recall that

$$
\begin{aligned}
\mathbf{u} \cdot \mathbf{v} & =0 \\
\mathbf{v} \cdot \mathbf{v} & =1 \\
\mathbf{w} \cdot \mathbf{v} & =0 .
\end{aligned}
$$

## The View Matrix

- And,

$$
\text { view } \cdot \mathbf{w}=\left(\begin{array}{cccc}
v_{11} & v_{12} & v_{13} & a \\
v_{21} & v_{22} & v_{23} & b \\
v_{31} & v_{32} & v_{33} & c \\
0 & 0 & 0 & 1
\end{array}\right)\left(\begin{array}{c}
w_{x} \\
w_{y} \\
w_{z} \\
0
\end{array}\right)=\left(\begin{array}{l}
0 \\
0 \\
1 \\
0
\end{array}\right)=\mathbf{k},
$$

- That is,

$$
\begin{aligned}
& \left(v_{11}, v_{12}, v_{13}\right) \cdot \mathbf{w}=0, \\
& \left(v_{21}, v_{22}, v_{23}\right) \cdot \mathbf{w}=0, \\
& \left(v_{31}, v_{32}, v_{33}\right) \cdot \mathbf{w}=1 .
\end{aligned}
$$

- That is,

$$
\begin{aligned}
& \left(v_{11}, v_{12}, v_{13}\right) \cdot \mathbf{w}=0, \\
& \left(v_{21}, v_{22}, v_{23}\right) \cdot \mathbf{w}=0, \\
& \left(v_{31}, v_{32}, v_{33}\right) \cdot \mathbf{w}=1 .
\end{aligned}
$$

- Recall that

$$
\begin{aligned}
\mathbf{u} \cdot \mathbf{w} & =0 \\
\mathbf{v} \cdot \mathbf{w} & =0 \\
\mathbf{w} \cdot \mathbf{w} & =1 .
\end{aligned}
$$

## The View Matrix

- Therefore, the view matrix will be of the form

$$
\mathbf{v}=\left(\begin{array}{cccc}
u_{x} & u_{y} & u_{z} & a \\
v_{x} & v_{y} & v_{z} & b \\
w_{x} & w_{y} & w_{z} & c \\
0 & 0 & 0 & 1
\end{array}\right),
$$

with $a, b$, and $c$ to be determined (the translation).

## The View Matrix

- To determine $a, b$, and $c$, use that fact that $\mathbf{V}$ also transforms $E$ to the origin:

$$
\mathrm{V} E=O
$$

- That is,

$$
\text { view } \cdot E=\left(\begin{array}{cccc}
u_{x} & u_{y} & u_{z} & a \\
v_{x} & v_{y} & v_{z} & b \\
w_{x} & w_{y} & w_{z} & c \\
0 & 0 & 0 & 1
\end{array}\right)\left(\begin{array}{c}
e_{x} \\
e_{y} \\
e_{z} \\
1
\end{array}\right)=\left(\begin{array}{l}
0 \\
0 \\
0 \\
1
\end{array}\right)=0 .
$$

## The View Matrix

- When we multiply, we get

$$
\left(\begin{array}{cccc}
u_{x} & u_{y} & u_{z} & a \\
v_{x} & v_{y} & v_{z} & b \\
w_{x} & w_{y} & w_{z} & c \\
0 & 0 & 0 & 1
\end{array}\right)\left(\begin{array}{c}
e_{x} \\
e_{y} \\
e_{z} \\
1
\end{array}\right)=\left(\begin{array}{c}
u_{x} e_{x}+u_{y} e_{y}+u_{z} e_{z}+a \\
v_{x} e_{x}+v_{y} e_{y}+v_{z} e_{z}+b \\
w_{x} e_{x}+w_{y} e_{y}+w_{z} e_{z}+c \\
1
\end{array}\right)
$$

## The View Matrix

- Thus,

$$
\begin{aligned}
& a=-\left(u_{x} e_{x}+u_{y} e_{y}+u_{z} e_{z}\right)=-\mathbf{u} \cdot \mathbf{e} \\
& b=-\left(v_{x} e_{x}+v_{y} e_{y}+v_{z} e_{z}\right)=-\mathbf{v} \cdot \mathbf{e} \\
& c=-\left(w_{x} e_{x}+w_{y} e_{y}+w_{z} e_{z}\right)=-\mathbf{w} \cdot \mathbf{e}
\end{aligned}
$$

where $\mathbf{e}=E-O$.

## The View Matrix

- Therefore, the matrix created by lookAt () is

$$
\text { view }=\left(\begin{array}{cccc}
u_{x} & u_{y} & u_{z} & -\mathbf{u} \cdot \mathbf{e} \\
v_{x} & v_{y} & v_{z} & -\mathbf{v} \cdot \mathbf{e} \\
w_{x} & w_{y} & w_{z} & -\mathbf{w} \cdot \mathbf{e} \\
0 & 0 & 0 & 1
\end{array}\right)
$$

## The View Matrix

- Verify that view transforms the points

$$
\begin{aligned}
E & \rightarrow(0,0,0) \\
E+\mathbf{u} & \rightarrow(1,0,0) \\
E+\mathbf{v} & \rightarrow(0,1,0) \\
E+\mathbf{w} & \rightarrow(0,0,1)
\end{aligned}
$$

## The lookAt () Function in vmath. h

The lookAt () Function in vmath. h
mat4 lookAt (const vec3\& eye, const vec3\& look, const vec3\& up)

```
vec3 w = normalize(look - eye);
vec3 upN = normalize(up);
vec3 u = normalize(cross(w, upN));
vec3 v = cross(u, w);
mat4 M = mat4(
    vec4(u[0], v[0], -w[0], 0),
    vec4(u[1], v[1], -w[1], 0),
    vec4(u[2], v[2], -w[2], 0),
    vec4(0, 0, 0, 1));
```

return $M$ * translate(-eye);

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(5) Assignment

## Finding the View Matrix

Example (Finding the View Matrix)

- Let $E=(16,15,12), L=(0,0,0)$, and $\mathbf{u p}=(0,1,0)$.
- Then


## Finding the View Matrix

Example (Finding the View Matrix)

- Let $E=(16,15,12), L=(0,0,0)$, and $\mathbf{u p}=(0,1,0)$.
- Then

$$
\mathbf{w}^{\prime}=E-L=(16,15,12)
$$

## Finding the View Matrix

Example (Finding the View Matrix)

- Let $E=(16,15,12), L=(0,0,0)$, and up $=(0,1,0)$.
- Then

$$
\begin{aligned}
\mathbf{w}^{\prime} & =E-L=(16,15,12) \\
\mathbf{w} & =\frac{\mathbf{w}^{\prime}}{\left|\mathbf{w}^{\prime}\right|}=\frac{1}{25}(16,15,12)
\end{aligned}
$$

## Finding the View Matrix

## Example (Finding the View Matrix)

- Let $E=(16,15,12), L=(0,0,0)$, and $\mathbf{u p}=(0,1,0)$.
- Then

$$
\begin{aligned}
& \mathbf{w}^{\prime}=E-L=(16,15,12) \\
& \mathbf{w}=\frac{\mathbf{w}^{\prime}}{\left|\mathbf{w}^{\prime}\right|}=\frac{1}{25}(16,15,12)=(0.64,0.60,0.48)
\end{aligned}
$$

## Finding the View Matrix

## Example (Finding the View Matrix)

- Let $E=(16,15,12), L=(0,0,0)$, and up $=(0,1,0)$.
- Then

$$
\begin{aligned}
& \mathbf{w}^{\prime}=E-L=(16,15,12) \\
& \mathbf{w}=\frac{\mathbf{w}^{\prime}}{\left|\mathbf{w}^{\prime}\right|}=\frac{1}{25}(16,15,12)=(0.64,0.60,0.48) \\
& \mathbf{u}^{\prime}=\mathbf{u p} \times \mathbf{w}=(0.48,0.00,-0.64)
\end{aligned}
$$

## Finding the View Matrix

## Example (Finding the View Matrix)

- Let $E=(16,15,12), L=(0,0,0)$, and $\mathbf{u p}=(0,1,0)$.
- Then

$$
\begin{aligned}
& \mathbf{w}^{\prime}=E-L=(16,15,12) \\
& \mathbf{w}=\frac{\mathbf{w}^{\prime}}{\left|\mathbf{w}^{\prime}\right|}=\frac{1}{25}(16,15,12)=(0.64,0.60,0.48) \\
& \mathbf{u}^{\prime}=\mathbf{u p} \times \mathbf{w}=(0.48,0.00,-0.64) \\
& \mathbf{u}=\frac{\mathbf{u}^{\prime}}{\left|\mathbf{u}^{\prime}\right|}=\frac{1}{0.80}(0.48,0.00,-0.64)
\end{aligned}
$$

## Finding the View Matrix

## Example (Finding the View Matrix)

- Let $E=(16,15,12), L=(0,0,0)$, and $\mathbf{u p}=(0,1,0)$.
- Then

$$
\begin{aligned}
\mathbf{w}^{\prime} & =E-L=(16,15,12) \\
\mathbf{w} & =\frac{\mathbf{w}^{\prime}}{\left|\mathbf{w}^{\prime}\right|}=\frac{1}{25}(16,15,12)=(0.64,0.60,0.48) \\
\mathbf{u}^{\prime} & =\mathbf{u p} \times \mathbf{w}=(0.48,0.00,-0.64) \\
\mathbf{u} & =\frac{\mathbf{u}^{\prime}}{\left|\mathbf{u}^{\prime}\right|}=\frac{1}{0.80}(0.48,0.00,-0.64)=(0.60,0.00,-0.80)
\end{aligned}
$$

## Finding the View Matrix

Example (Finding the View Matrix)

- Let $E=(16,15,12), L=(0,0,0)$, and up $=(0,1,0)$.
- Then

$$
\begin{aligned}
& \mathbf{w}^{\prime}=E-L=(16,15,12) \\
& \mathbf{w}=\frac{\mathbf{w}^{\prime}}{\left|\mathbf{w}^{\prime}\right|}=\frac{1}{25}(16,15,12)=(0.64,0.60,0.48) \\
& \mathbf{u}^{\prime}=\mathbf{u p} \times \mathbf{w}=(0.48,0.00,-0.64) \\
& \mathbf{u}=\frac{\mathbf{u}^{\prime}}{\left|\mathbf{u}^{\prime}\right|}=\frac{1}{0.80}(0.48,0.00,-0.64)=(0.60,0.00,-0.80) \\
& \mathbf{v}=\mathbf{w} \times \mathbf{u}=(-0.48,0.80,-0.36)
\end{aligned}
$$

## Finding the View Matrix

Example (Finding the View Matrix)

- To summarize,

$$
\begin{aligned}
\mathbf{u} & =(+0.60,+0.00,-0.80) \\
\mathbf{v} & =(-0.48,+0.80,-0.36) \\
\mathbf{w} & =(+0.64,+0.60,+0.48)
\end{aligned}
$$

## Finding the View Matrix

Example (Finding the View Matrix)

- Also

$$
\mathbf{e}=E-O=(16,15,12)
$$

- So

$$
\begin{aligned}
\mathbf{e} \cdot \mathbf{u} & =0 \\
\mathbf{e} \cdot \mathbf{v} & =0 \\
\mathbf{e} \cdot \mathbf{w} & =25
\end{aligned}
$$

## Finding the View Matrix

## Example (Finding the View Matrix)

- Therefore, the view matrix is

$$
\mathbf{V}=\left(\begin{array}{cccc}
+0.60 & +0.00 & -0.80 & 0 \\
-0.48 & +0.80 & -0.36 & 0 \\
+0.64 & +0.60 & +0.48 & -25 \\
0 & 0 & 0 & 1
\end{array}\right)
$$

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## Homework

## Homework

- The Red Book, p. 220.
- See Transformation Matrix.
- See Camera Transformation.

